

## Freeform Search

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<b>Database:</b>	<div style="border: 1px solid black; padding: 2px;">         US Pre-Grant Publication Full-Text Database          US Patents Full-Text Database          US OCR Full-Text Database          EPO Abstracts Database          JPO Abstracts Database          Derwent World Patents Index          IBM Technical Disclosure Bulletins       </div>
<b>Term:</b>	<div style="border: 1px solid black; padding: 2px;">         L32 and driv\$6 adj signal\$6       </div>
<b>Display:</b>	<div style="border: 1px solid black; padding: 2px;">         20 Documents in <u>Display Format:</u> <div style="border: 1px solid black; padding: 0 5px;">TI</div> Starting with Number <div style="border: 1px solid black; padding: 0 5px;">1</div> </div>
<b>Generate:</b> <input type="radio"/> Hit List <input checked="" type="radio"/> Hit Count <input type="radio"/> Side by Side <input type="radio"/> Image	

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Search

Clear

Interrupt

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### Search History

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**DATE:** Tuesday, July 10, 2007  
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<u>Set</u> <u>Name</u> side by side	<u>Query</u>	<u>Hit</u> <u>Count</u>	<u>Set</u> <u>Name</u> result set
	<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<u>L43</u>	L32 and driv\$6 adj signal\$6	5	<u>L43</u>
<u>L42</u>	L32 and drive\$6 adj signal\$6	3	<u>L42</u>
<u>L41</u>	l32 and operation adj mode\$6	1	<u>L41</u>
<u>L40</u>	l32 and (plural\$6 or different or multiple) near4 drive\$6 adj signal\$1	1	<u>L40</u>
<u>L39</u>	l30 and plural\$6 near4 drive\$6 adj signal\$1	0	<u>L39</u>
<u>L38</u>	l33 and plural\$6 near4 drive\$6 adj signal\$1	0	<u>L38</u>
<u>L37</u>	l33 and plural\$6 adj drive\$6 adj signal\$1	0	<u>L37</u>
<u>L36</u>	l33 and plural\$6 adj drive\$6 signal\$1	0	<u>L36</u>
<u>L35</u>	l32 and first same second adj driv\$6 adj signal\$1	1	<u>L35</u>
<u>L34</u>	l33 and drive\$6 adj signal\$1	2	<u>L34</u>
<u>L33</u>	L32 and @py<=2002	20	<u>L33</u>
<u>L32</u>	first adj electro-mechanical adj transducer\$1 same second adj electro-mechanical adj transducer\$1	24	<u>L32</u>
<u>L31</u>	L30 and feedback adj signals	14	<u>L31</u>
<u>L30</u>	L29 and @py<=2002	332	<u>L30</u>

<u>L29</u>	electro-mechanical adj transducer\$1 same first same second	353	<u>L29</u>
<u>L28</u>	L27 and haptic	1	<u>L28</u>
<u>L27</u>	electro-mechanical adj transducer\$1 same (first or second)	592	<u>L27</u>
<u>L26</u>	l22 and feedback adj signal\$1	1	<u>L26</u>
<u>L25</u>	l22 and feedback adj signal\$1	1	<u>L25</u>
<u>L24</u>	l22 and haptic	1	<u>L24</u>
<u>L23</u>	L22 and @py<=2002	48	<u>L23</u>
<u>L22</u>	electro-mechanical adj transducer\$1 same piezoelectric adj transducer\$1	54	<u>L22</u>
<u>L21</u>	L20 and @py<=2002	0	<u>L21</u>
<u>L20</u>	electro-active adj polymer same transducer\$1	18	<u>L20</u>
<u>L19</u>	L18 and @py<=2002	0	<u>L19</u>
<u>L18</u>	electro-active adj polymer and transducer\$1	54	<u>L18</u>
<u>L17</u>	electro-active adj polymer and electro-mechanical adj transducer	1	<u>L17</u>
<u>L16</u>	electro-active adj polymer same electro-mechanical adj transducer	1	<u>L16</u>
<u>L15</u>	electro-active adj polymer	292	<u>L15</u>
<u>L14</u>	l1 and electro-active adj polymer	1	<u>L14</u>
<u>L13</u>	l2 and electro-active adj polymer	1	<u>L13</u>
<u>L12</u>	L11 and @py<=2002	15	<u>L12</u>
<u>L11</u>	l2 and piezoelectric adj transducer\$1	17	<u>L11</u>
<u>L10</u>	L8 and resonant adj mode\$1	4	<u>L10</u>
<u>L9</u>	L8 and resonant	32	<u>L9</u>
<u>L8</u>	L7 and @py<=2002	50	<u>L8</u>
<u>L7</u>	electro-mechanical adj transducer\$1 same modes same vibrat\$6 same frequenc\$6	50	<u>L7</u>
<u>L6</u>	l3 and vibrat\$6 same frequenc\$6	80	<u>L6</u>
<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI; PLUR=YES; OP=ADJ</i>			
<u>L5</u>	electro-mechanical adj transducer\$6 same resonant adj mode\$6	5	<u>L5</u>
<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>			
<u>L4</u>	l3 and resonant adj mode\$1	9	<u>L4</u>
<u>L3</u>	L2 and @py<=2002	137	<u>L3</u>
<u>L2</u>	electro-mechanical adj transducer\$1 same modes	147	<u>L2</u>
<u>L1</u>	electro-mechanical adj transducer\$1	1949	<u>L1</u>

END OF SEARCH HISTORY

## Freeform Search

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	JPO Abstracts Database
	Derwent World Patents Index
	IBM Technical Disclosure Bulletins

  

<b>Term:</b>	electro-mechanical adj transducer\$1 same (various or different or multiple or multi) adj modes	▲ ▼
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<b>Display:</b>	<input type="text" value="20"/> Documents in <b>Display Format:</b> <input type="text" value="TI"/> <b>Starting with Number</b> <input type="text" value="1"/>
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**Generate:** ☐ Hit List ☒ Hit Count ☐ Side by Side ☐ Image

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<u>Set</u> <u>Name</u> side by side	<u>Query</u>	<u>Hit</u> <u>Count</u>	<u>Set</u> <u>Name</u> result set
	<i>DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<u>L15</u>	electro-mechanical adj transducer\$1 same (various or different or multiple or multi) adj modes	5	<u>L15</u>
<u>L14</u>	electro-mechanical adj transducer\$1 same operational adj modes	3	<u>L14</u>
<u>L13</u>	L12 and @py<=2002	137	<u>L13</u>
<u>L12</u>	electro-mechanical adj transducer\$1 same modes	147	<u>L12</u>
<u>L11</u>	electro-mechanical adj transducer\$1 and multi-mode	6	<u>L11</u>
<u>L10</u>	electro-mechanical adj transducer\$1	1949	<u>L10</u>
<u>L9</u>	L8 and @py<=2002	8	<u>L9</u>
<u>L8</u>	haptic adj feedback same transduce\$1	28	<u>L8</u>
<u>L7</u>	haptic adj feedback and electro-mechanical adj transduce\$1	3	<u>L7</u>
<u>L6</u>	haptic adj feedback same electro-mechanical adj transduce\$1	2	<u>L6</u>
<u>L5</u>	haptic adj feedback	1106	<u>L5</u>
<u>L4</u>	haptic adj feedback adj signal\$1	50	<u>L4</u>
<u>L3</u>	electro-mechanical adj transducer\$1 and haptic adj feedback adj signal\$1	2	<u>L3</u>
	electro-mechanical adj transducer\$1 same haptic adj feedback adj		